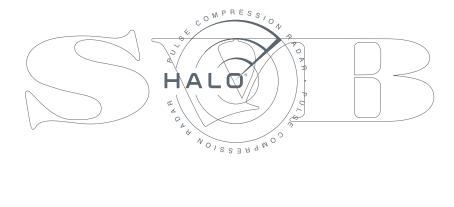


Halo® Pulse Compression Radar Installation Manual



ENGLISH

simrad-yachting.com



Preface

As Navico is continuously improving this product, we retain the right to make changes to the product at any time which may not be reflected in this version of the manual. Please contact your nearest distributor if you require any further assistance.

It is the owner's sole responsibility to install and use the instrument and transducers in a manner that will not cause accidents, personal injury or property damage. The user of this product is solely responsible for observing safe boating practices.

NAVICO HOLDING AS AND ITS SUBSIDIARIES, BRANCHES AND AFFILIATES DISCLAIM ALL LIABILITY FOR ANY USE OF THIS PRODUCT IN A WAY THAT MAY CAUSE ACCIDENTS, DAMAGE OR THAT MAY VIOLATE THE LAW.

Governing Language: This statement, any instruction manuals, user guides and other information relating to the product (Documentation) may be translated to, or has been translated from, another language (Translation). In the event of any conflict between any

Translation of the Documentation, the English language version of the Documentation will be the official version of the Documentation.

This manual represents the product as at the time of printing. Navico Holding AS and its subsidiaries, branches and affiliates reserve the right to make changes to specifications without notice.

Copyright

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Warranty

The warranty card is supplied as a separate document.

In case of any queries, refer to the brand web site of your display or system:

www.simrad-yachting.com

Declarations and conformance

This equipment is intended for use in international waters as well as coastal sea areas administered by countries of the E.U. and E.E.A.

Compliance Statements

The Simrad Halo® pulse compression radar,

- * Comply with CE under R&TTE directive 1999/5/EC.
- * The relevant Declaration of Conformity is available in the following website under model documentation section:

www.simrad-yachting.com

FCC Warning Statement

FCC Part 15.19 Warning Statement

THIS DEVICE COMPLIES WITH PART 15 OF THE FCC RULES. OPERATION IS SUBJECT TO THE FOLLOWING TWO CONDITIONS: (1) THIS DEVICE MAY NOT CAUSE HARMFUL INTERFERENCE, AND (2) THIS DEVICE MUST ACCEPT ANY INTERFERENCE RECEIVED, INCLUDING INTERFERENCE THAT MAY CAUSE UNDESIRED OPERATION.

FCC Part 15.21 Warning Statement

NOTE: NAVICO INC. IS NOT RESPONSIBLE FOR ANY CHANGES OR MODIFICATIONS NOT EXPRESSLY APPROVED BY THE PARTY RESPONSIBLE FOR COMPLIANCE. SUCH MODIFICATIONS COULD VOID THE USER'S AUTHORITY TO OPERATE THE EQUIPMENT.

FCC Part 15.105(b) Warning Statement

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there

is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- -Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- -Consult the dealer or an experienced radio/TV technician for help.

INDUSTRY CANADA WARNING STATEMENTS:

IC RSS-GEN, Sec 7.1.3 Warning Statement

ENGLISH:

This device complies with Industry Canada license-exempt RSS standard(s). Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

FRENCH:

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes : (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

IC RSS-GEN, Sec 7.1.2 Warning Statement

ENGLISH:

Under Industry Canada regulations, this radio transmitter may only oberate using an antenna of a type and maximum (or lesser) gain approved for the transmitter by Industry Canada. To reduce potential radio interference to other users, the antenna type and its gain should be so chosen that the equivalent isotropically radiated power (e.i.r.p.) is not more than that necessary for successful communication.

FRENCH:

Conformément à la réglementation d'Industrie Canada, le présent émetteur radio peut fonctionner avec une antenne d'un type et d'un gain maximal (ou inférieur) approuvé pour l'émetteur par Industrie Canada. Dans le but de réduire les risques de brouillage radioélectrique à l'intention des autres utilisateurs, il faut choisir le type d'antenne et son gain de sorte que la puissance isotrope rayonnée quivalente (p.i.r.e.) ne dépassepas l'intensité nécessaire à l'établissement d'une communication satisfaisante.

IC RSS-GEN, Sec 7.1.2 Warning Statement

ENGLISH:

This radio transmitter – Halo™ Pulse Compression Radar – (4697A-HALO) has been approved by Industry Canada to operate with the antenna types listed below with the maximum permissible gain and required antenna impedance for each antenna type indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.

FRENCH:

Le présent émetteur radio – Halo™ Pulse Compression Radar – (4697A-HALO) a été approuvé par Industrie Canada pour fonctionner avec les types d'antenne énumérés ci-dessous et ayant un gain admissible maximal et l'impédance requise pour chaque type d'antenne. Les types d'antenne non inclus dans cette liste, ou dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

Halo Antennas:	Description:	Max. permissible antenna gain (dBi):	Impedance:
000-11464-001	Antenna, 3ft, Halo	26	50 Ohm (WR-90 Waveguide)
000-11465-001	Antenna, 4ft, Halo	27.2	50 Ohm (WR-90 Waveguide)
000-11466-001	Antenna, 6ft, Halo	29	50 Ohm (WR-90 Waveguide)

CE Compliance Statement

Countries of intended use in LI - Liechtenstein the EU: IV - Latvia AT - Austria LT - Lithuania BE - Belgium LU - Luxembourg BG - Bulgaria MT - Malta CY - Cyprus NL - Netherlands CZ - Czech Republic NO - Norway DK - Denmark PL - Poland EE - Estonia PT - Portugal FI - Finland RO - Romania FR - France SK - Slovakia DE - Germany SI - Slovenia GR - Greece ES - Spain HU - Hungary SE - Sweden IS - Iceland CH - Switzerland IE - Ireland TR - Turkey IT - Italy UK - United Kingdom

→ Note: Most countries accept that RF power density levels below 100 W/m2 cause no significant RF hazard.

Radio Frequency (RF) Exposure Information

Calculations for radar systems in table below show that the safe distance (for a rotating antenna) is within the antenna's turning circle. Irrespective users should stay well outside the turning circle of the antenna to avoid injury through impact as it spins

System	100 W /m2 Occupational safe distance	10 W /m2 Public safe distance
All Halo™ Radars	0 cm (0 ft)	28 cm (0.92 ft)

Trademarks

- NMEA 2000 is a registered trademark of the National Marine Electronics Association
- Simrad is a trademark of Kongsberg Maritime AS Company registered in the US and other countries and is being used under license
- B&G, Lowrance, StructureScan, Navico, SonicHub, SimNet, Skimmer, InsightHD, Halo Pulse Compression Radar, Broadband Radar and Broadband Sonar are trademarks of Navico, registered in the US and other countries

About this manual

This manual is a reference guide for installing the Simrad Halo pulse compression radar.

The manual does not cover basic background information about how equipment such as radars, echosounders and AIS work. Such information is available from our web site:

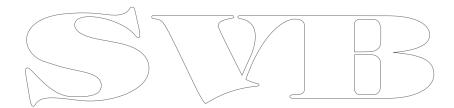
www.support.simrad-yachting.com

Important text that requires special attention from the reader is emphasized as follows:

→ *Note*: Used to draw the reader's attention to a comment or some important information.

Warning: Used when it is necessary to warn personnel that they should proceed carefully to prevent risk of injury and/or damage to equipment/personnel.

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Contents

8 Introduction

9 Check the parts

- 9 Pedestal
- 10 Antenna
- 10 RI-12 Radar interface module

11 Tools required

12 Installation Guidelines

- 13 Compass safe distance
- 13 Multi-radar installations
- 13 Power boat installations
- 14 Considerations for direct roof mounting

15 Hardware mounting

- 15 Install the RI-12 radar Interface module
- 16 Install the pedestal
- 20 Fitting the antenna to the pedestal

21 Wiring

- 22 RI-12 connections
- 23 LED Indicator lights
- 23 Pedestal Interconnection cable
- 26 Grounding requirements
- 27 Remote power control
 - Network

28

30

- 29 NMEA 2000
 - NMEA 0183
- 30 RI-12 heading source selection:
- 30 Antenna park

32 Setup and configuration

- 32 Entering radar setup on your display
- 32 Select the antenna length
- 32 Adjust antenna height...
- 33 Adjust bearing alignment...
- 34 Sector blanking
- 34 Adjust open array park angle
- 34 Sidelobe suppression...
- 35 Radar Status
- 35 Reset Radar to factory defaults
- 36 Control pedestal accent lighting

37 Specifications

39 Drawings

- 39 RI-12
- 40 Pedestal and antennas

42 Spare Parts

43 Third party mounting options

Introduction

1

This manual explains how to install the Halo® Pulse Compression Radar system. This manual should be used in conjunction with the installation manual provided with the display.

This manual is written for professional marine technicians, installation technicians, and service technicians. Dealers may use information contained in this document.

The Halo® Pulse Compression Radar combines the best characteristics of traditional pulse and FMCW broadband radar systems, our Halo™ Radar uses Pulse Compression technology to provide an unprecedented mix of long and short detection range, high target definition, and minimal clutter. Solid State technology means minimal warm-up time and maximum oceangoing reliability, while compliance with upcoming Low Emission standards makes Halo Radar safe to run in anchorages and marinas

The radar system consists of a pedestal, antenna, RI-12 radar interface and connection cables. An Ethernet network cable is used to connect the RI-12 radar interface module to the navigation Ethernet network and is intended for use in a marine environment.

- → *Note:* Antennas are available in three sizes 3 ft, 4 ft and 6 ft to suit customer requirements.
- → **Note:** At the time of release the Halo radar will only work with Simrad NSSevo2 and NSOevo2 systems
- → *Note:* The radar should be installed by a qualified radar technician.

Warnings

Warning: Use the radar at your own risk. Your radar is designed as a navigation aid. Always compare the navigation information received from your radar with data from other navigation aids and sources. When a conflict arises between the navigation data from your radar and data from other navigation aids, make sure you resolve the conflict before proceeding with navigation.

A CAREFUL NAVIGATOR NEVER RELIES ON ONLY ONE METHOD TO OBTAIN NAVIGATION INFORMATION.

International Regulations for Preventing Collisions at Sea mandate that when radar is on a vessel, the radar must be used at all times, regardless of weather conditions or visibility. Numerous court decisions have ruled that the radar must be used, and the radar operator must know all operational aspects of radar performance. Otherwise they will face a greater risk of liability if an accident occurs.

Warning: High Current, Stored and Microwave Energy Hazard. Technicians must exercise extreme care when working inside the unit. ALWAYS remove power before removing the cover. Some capacitors may take several minutes to discharge, even after switching off the radar. Before touching any high voltage components, ground them with a clip lead.

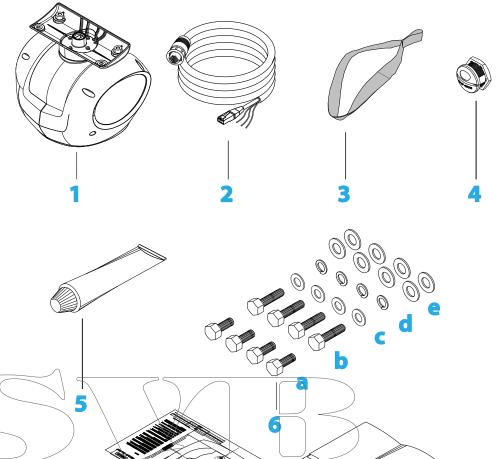
Warning: Halo™ Pulse Compression Radar's blue 4 level static accent pedestal lighting may not be approved for use in your boating location. Please check your local boating regulations before turning the blue accent lights ON.

Warning: The microwave energy radiated by a radar antenna is harmful to humans, especially to the eyes. NEVER look directly into an open waveguide or into the path of radiation from an enclosed antenna. Remove power or use the Safety switch on the rear of the Pedestal to turn off the radar whenever it is necessary to work on the antenna unit or other equipment in the beam of the radar.

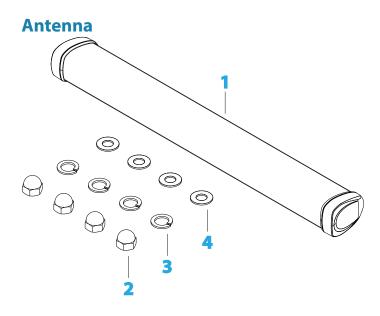
7

Check the parts

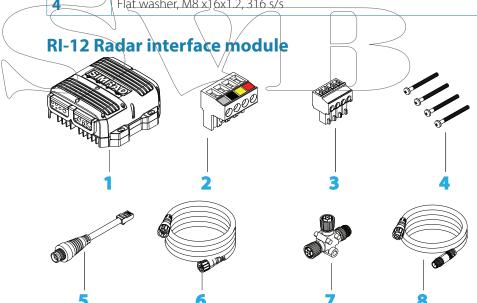
Pedestal



1	Radar pedestal		
2	Interconnection cable 20 m (65 ft) (other lengths available)		
3	Lifting strap		
4	Blanking plug (used when interconnection cable connected underneath the pedestal. Blanking plug is fitted underneath when shipped)		
5	Anti-seize grease		
6	Mounting Bolts and washers		
	a) Bolts, hex head, M12 x 35 mm, 316 s/s	x 4	
	b) Bolts, hex head , M12 x 50 mm, 316 s/s x4		
	c) Flat washer, M12 x 36 x 3, 316 s/s x4		
	d) Spring washer, M12, 316 s/s x4		
	e) Isolating washer, M12 x 38	x8	
7	Drill template		
8	This manual		



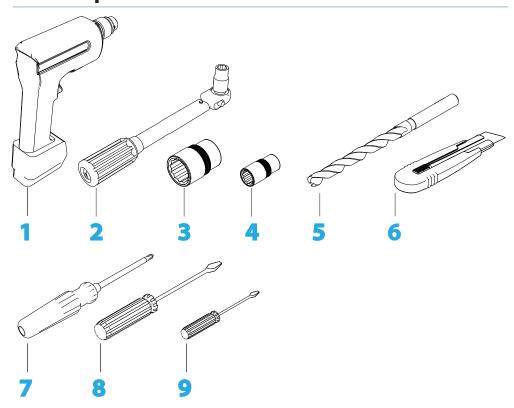
No.	Description		
1	Radar antenna 3 ft (3.70 ft Antenna 1127 mm (44.37"))		
	4 ft (4.70 ft Antenna 1431 mm (56.34"))		
	6 ft (6.69 ft Antenna 2038 mm (80.24"))		
2	Dome nuts, M8, 316 s/s		
3	Spring washer, M8, 316 s/s		
4	Flat washer, M8 x16x1.2, 316 s/s		



No.	Description	
1	RI-12 Radar interface module	
2	Connector for the pedestal interconnection cable	
3	Connector for Aux In (NMEA 0183, remote power and park brake)	
4	Mounting hard ware	
5	Ethernet adapter. RJ45 male to 5 pin female 150 mm (5.9")	
6	Ethernet cable 1.8 m (6 ft)	
7	Micro-CT Joiner	
8	Micro-C drop cable 1.8 m (6 ft)	

2

Tools required



No.	Description
1	Drill\
2	Torque wrench
3	19 mm socket
4	13 mm socket
5	Drill bit 12.5 mm (1/2")
6	Sharp Knife
7	Screw driver (pozidrive)
8	Screw driver (flat blade)
9	Screw driver (flat blade, small)

Warning: A radar unit should only be installed by a qualified marine technician, as improper installation poses risks to the installer, the public, and to the safety of the vessel.

Warning: Before commencing any installation or maintenance on the Halo radar make sure the safety switch on the rear of the pedestal is set to OFF

There is a transmit interlock that prevents radar transmissions if the scanner is not rotating. However, a high voltage remains for a period of time after the system is turned off. If you are not familiar with this type of electronics, consult with a trained service or installation technician before attempting to service any part of the equipment.

Installation includes:

- mechanical mounting
- electrical wiring
- configuring the display or network system to work with the radar
- adjusting the radar for proper performance

The radar's ability to detect targets depends greatly on the position of its scanner. The ideal location for the scanner is high above the vessel's keel line where there are no obstacles.

A higher installation position increases the radar ranging distance, but it also increases the minimum range around the vessel where targets cannot be detected and increases seaclutter pick up

When you're deciding on the location, please consider:

- The length of the 20 m (66 ft) interconnection cable supplied with the radar is usually sufficient. A longer 30 m (98 ft) cable is available 30 m (98 ft) is the longest the cable that can be used.
- If the roof of the wheelhouse is the highest existing location, consider installing a radar mast or tower on which you can mount the radar. You may also need to construct a working platform for your own safety during installation and servicing work.
- If you locate the scanner on the mast, position it on the forward side so that there is a clear view to the front of the vessel.
- It is preferable to install the scanner parallel to the line of the keel.

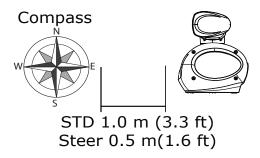
DO NOT DO THIS!

- DO NOT install the scanner too high up, where its weight will alter the stability of the vessel and cause degrade the radar picture over short ranges.
- DO NOT install the scanner close to lamps or exhaust outlets. The heat emissions may cause the equipment to break down. Soot and smoke will degrade the performance of the radar.
- DO NOT install the scanner close to the antennas of other equipment such as direction finders, VHF antennas, GPS equipment etc, as it may cause interference.
- DO NOT install the scanner where a large obstruction (such as an exhaust stack) is at the same level as the beam. The obstruction is likely to generate false echoes and/or shadow zones. If no other alternative location use the sector blanking feature in the radar software. (see "" on page 33)
- DO NOT install the scanner where it will be subjected to strong vibrations because the vibrations could degrade the performance of the radar.
- DO NOT install an open array close to halyards or flags because the wind could wrap these around the antenna and jam it.

Compass safe distance

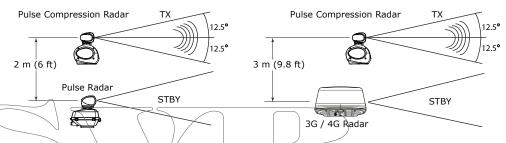
Warning: Do not install the scanner inside of the recommended compass safe distances of any navigation instruments such as the magnetic compass and the chronometer. The compass safe distances are as follows:

Minimum distance to install near the ships compass is 1.0m (3.3 ft).



Multi-radar installations

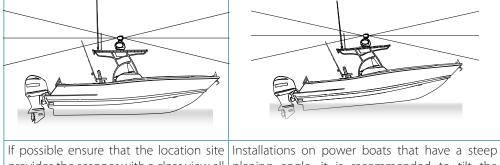
Vertical Separation



Do not install the Halo® pulse compression radar on the same beam plane as a conventional pulse radar. A pulse radar must be set to STBY or OFF any time the Halo® radar is being operated.

Note: Possible interference could be reduced by using the sector blanking feature (see "" on page 33)

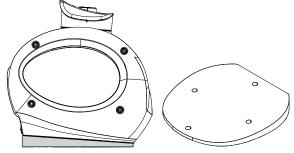
Power boat installations



If possible ensure that the location site provides the scanner with a clear view all round the vessel.

Installations on power boats that have a steep planing angle, it is recommended to tilt the scanner angle down at the front. (Beam angle is 12.5° either side of center).

→ *Note*: Optional 4 degree wedge available from third party suppliers such as SeaView RW4-7

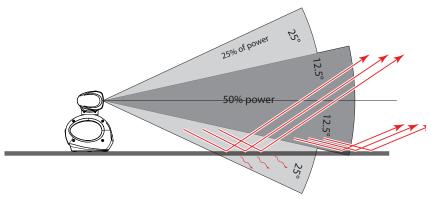


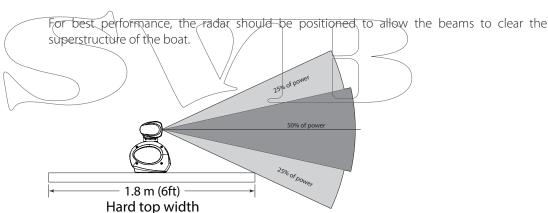
Considerations for direct roof mounting

When deciding a suitable mounting location for the Halo® Pulse Compression Radar be aware that the vertical radar beam extends to 25° either side of horizontal. With 50% of the power projecting in a beam 12.5° off horizontal. If the radar beams cannot clear the roof line, this will decrease performance of the radar. Depending on the size of the hard top of the vessel, it is recommended to elevate the antenna to allow the radar beams to clear the roof line. Below are guide lines on heights above the hard top.

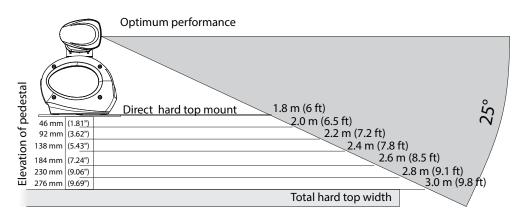
The below illustrates an installation with the Halo® Pulse Compression Radar mounted directly on to a large hard top. This installation could suffer decreased performance as the radar energy is either reflected or absorbed by the hard top.

→ **Note:** Where the mounting surface is constructed of any form of metal you must elevate the dome so that the beam has complete clearance, else performance will be severely impaired.





Below is a guide to determine the antenna height in relation to a vessels hard top overall width. Every Increase of 200 mm (7.9") of hard top total width over 1.8m wide: Increase the height of the antenna by 46 mm (1.8")



There are many radar mounting options available from third party vendors such as Seaview, Scanstrut and Edson. (see "Third party mounting options" on page 43)

4

Hardware mounting

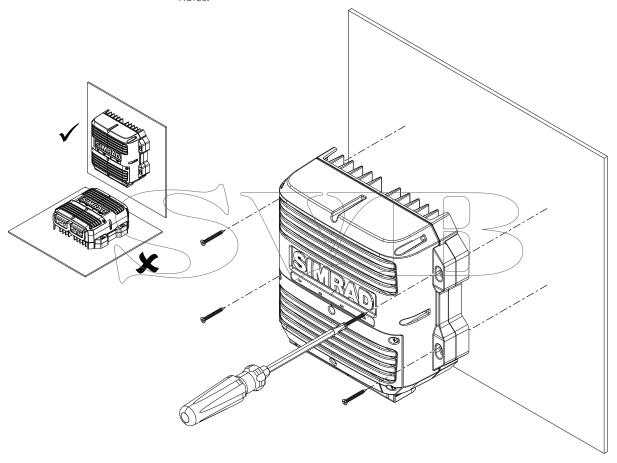
Install the RI-12 radar Interface module

Install the RI-12 in a dry location away from spray, rain, drips and condensation or excessive heat. The mounting position should be easily accessible.

Always mount the RI-12 vertically, with the cable entry points facing downwards. This is to assist in cooling and to assist stopping any possible water ingress though the cable grommets.

The RI-12 must be located where it can be easily connected to the ship's ground, the pedestal interconnection cable, the power cable and the NMEA 2000 network. Check that these cables and the ship's ground can easily reach the radar processor BEFORE you drill.

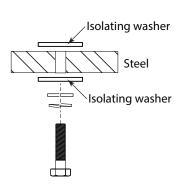
Use fasteners suited to the mounting surface material. If the material is too thin for self tappers, reinforce it, or mount the RI-12 with machine screws nuts and washers. Use only 304 or 316 stainless steel fasteners. Mark the screw locations using RI-12 box as a template, and drill pilot holes.

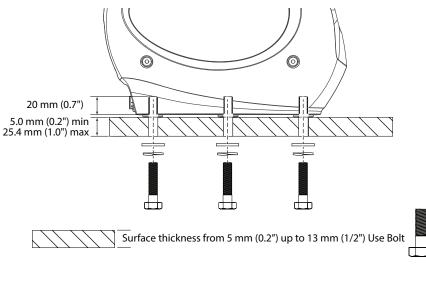


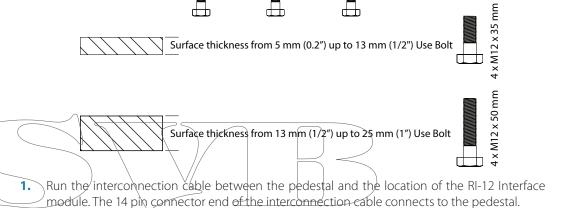
Install the pedestal

The eight hex head bolts supplied are suitable for surfaces up to 25 mm (1") in thickness. Use the $4 \times M12 \times 35$ mm for a surface thickness from 5 mm (0.2") up to 13 mm (1/2") Use the 4 x M12 x 50 mm for surface thickness from 13 mm (1/2") up to 25 mm (1") If using longer bolts make sure they are of marine grade stainless steel and allow for minimum of 12 mm (0.3") and maximum of 20 mm (0.7") of thread contact.

For steel boats use the supplied isolating washers

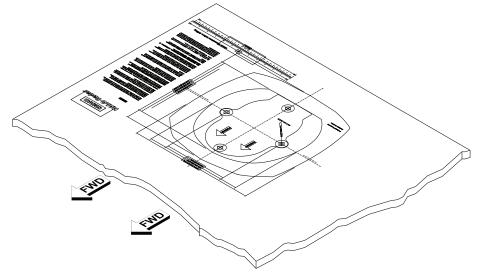




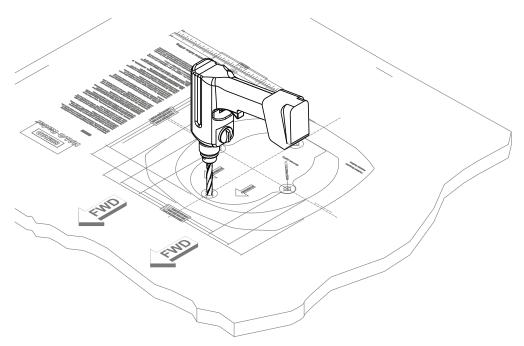


Surface thickness from 13 mm (1/2") up to 25 mm (1") Use Bolt

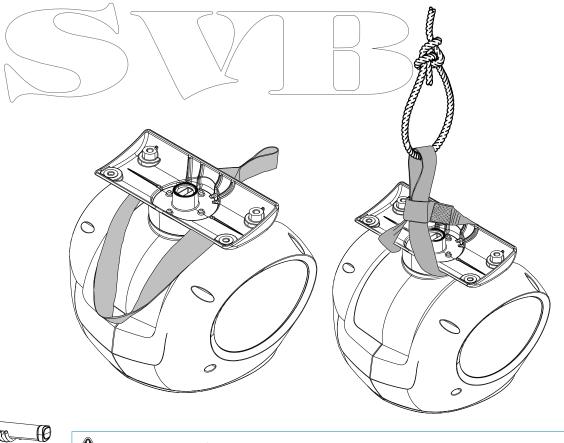
- **Note:** Protect the connectors especially the RJ45 connector when pulling cable through the boat and avoid putting strain on to the connectors
- → Note: The interconnection cable is 9 mm in diameter. A 14 mm hole will be required in order for the RJ45 connector end to pass through to the RI-12 or 24 mm for the 14 pin connector to pass through to the pedestal..
- 2. Stick down the mounting template in the desired installation location, observing correct orientation. (Minor deviation can be compensated for in the radar software).



3. Drill pilot holes, Then use a 12.5 mm (1/2") drill bit to drill the four holes where shown on the mounting template.



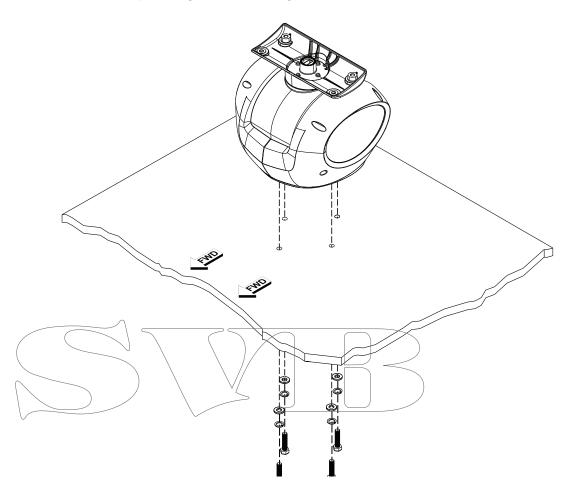
- **4.** Remove the mounting template .
- **5.** Lift the pedestal into position using the supplied lifting strap.



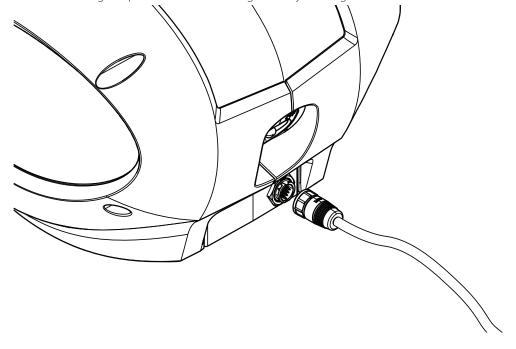
Warning: Do not lift the pedestal with the antenna attached

Surface mount: Rear cable connection

- 1. Position the scanner carefully over the bolt holes so that they are aligned.
- 2. Place a flat washer and spring washer onto each bolt, as shown.
- **3.** Insert bolts into the drilled holes and locate into the pedestals threaded mounting holes and tighten securely.
 - → Note: The torque settings for the mounting bolts are 30 N.m 40 N.m (22.1 ft-lbf 39.5 ft-lbf).



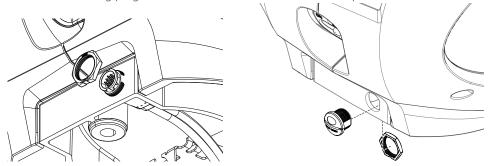
4. Connect the 14 pin end of the interconnection cable. Take care to align the connector correctly to avoid bending the pins. Secure the locking collar by rotating clockwise until it clicks.



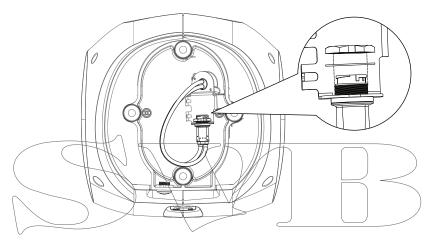
Pole or tower mount: Discreet cable connection

The interconnection cable can be optionally connected discreetly underneath the pedestal by moving the 14 pin connector at the rear of the pedestal to a bracket underneath the pedestal.

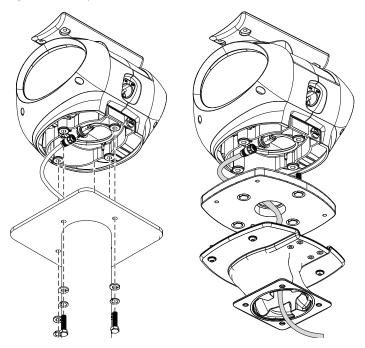
- 1. Remove the retaining nut and pull back the connector and fly lead.
- 2. Fit the supplied blanking plug where the connector used to be.
- → *Note:* The blanking plug is attached the bracket underneath the pedestal.



3. Re-route the internal fly lead to the bracket and secure with the nut.



- **4.** Connect the interconnection cable. Take care to align the connector correctly to avoid bending the pins. Secure the locking collar by rotating clockwise until it clicks.
- 5. Lower the pedestal carefully over the bolt holes so that they are aligned.
- 6. Place a flat washer and spring washer onto each bolt, as shown.
- **7.** Insert bolts into the drilled holes and locate into the pedestals threaded mounting holes and tighten securely.



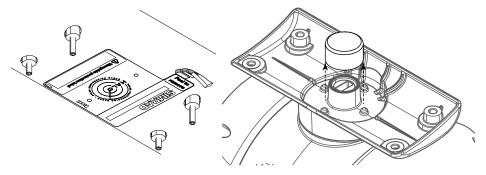
Fitting the antenna to the pedestal

Remove the protective cap from the pedestal and the protective label on the antenna that 1. protects the wave guide.

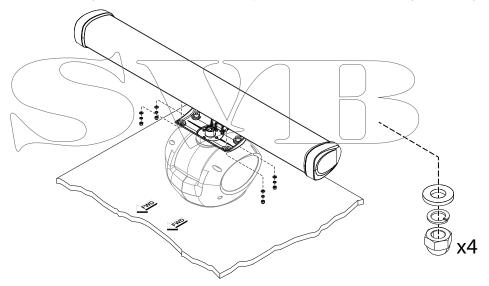


Warning: Do not operate the radar without the antenna connected.

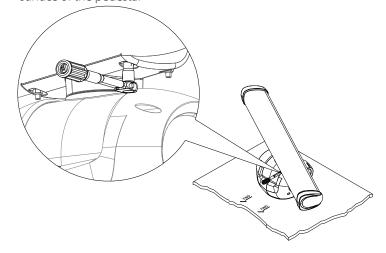
- → Note: The protection label and waveguide cover is in place to prevent contaminants from entering the waveguide. These covers MUST BE REMOVED IMMEDIATELY PRIOR TO INSTALL-ING THE ANTENNA TO THE PEDESTAL.
- → Note: An antenna Sealing Ring is located under this label in the antenna waveguide chamber. Ensure the Sealing Ring remains in place prior to installing the antenna to the pedestal.



3. Carefully lower the antenna on to the pedestal. The antenna can only fit one way



- Place a flat washer then a split washer followed by a dome nut on to each of the four antenna studs. Tighten the dome nuts using socket and torque wrench to 15 N.m (11 ft-lbf)
- → Note: A socket wrench is recommended to minimise risk of chipping the powder coated surface of the pedestal



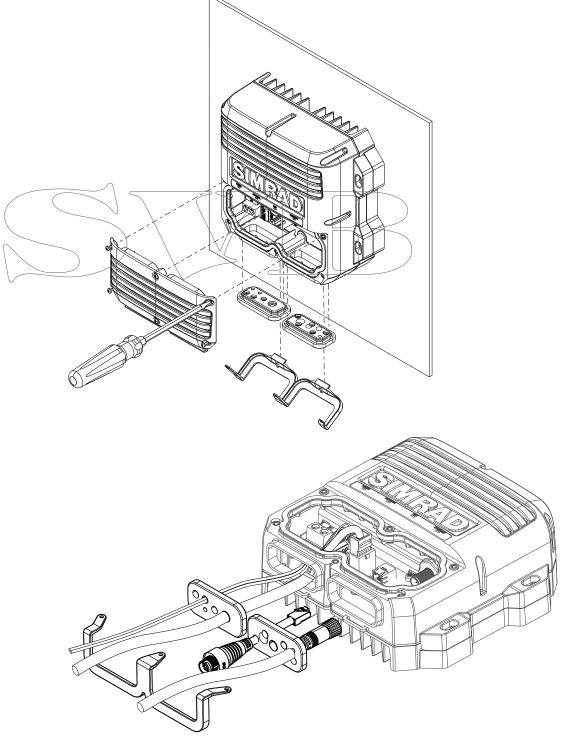
5

Wiring

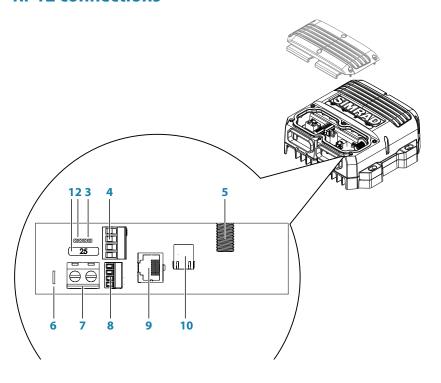
Warning: SAFETY SWITCH. The pedestal unit has a safety switch, which removes power from the radar and disables the antenna rotating during maintenance and service. Make sure switch is set to off before commencing installation and back to ON after completion

All wiring connections are made inside the RI-12 interface box. It is necessary to remove the lid to gain access to the connections

- 1. Remove the lid by unscrewing the six retaining screws
- 2. Remove the grommet retaining clip
- **3.** Remove the rubber grommets
- **4.** Pass the cables through the rubber grommets and into the RI-12. Use a sharp knife to cut a slit the grommet.



RI-12 connections



No.	Name	Description
1	FUSE	25 Amp blade fuse
3	Power control: REMOTE Power control: AUTO	Remote power control activation jumper. Move to REMOTE position so radar power state is controlled by a multifunction display or switch (see "Remote power control" on page 27) Radar will turn on when power is applied to the
		main power connector. Remote power wire on AUX IN port is ignored
4	SCANNER POWER	Large green connector: Provides 36 V DC up to the pedestal and power for the park brake. Connect the four wires of the interconnection cable matching the color coded sticker on the connector
5	NMEA 2000	Micro-C: NMEA 2000 network connection
6	SCREEN	Alternative chassis ground connection (see "Grounding requirements" on page 26)
7	- SUPPLY+	12 or 24 V DC input
8	AUX IN	Small connector: NMEA 0183 data input, remote power on and DC input for the antenna park brake
9	SCANNER	RJ45: Ethernet data from the pedestal. Connect the RJ45 connector of the interconnection cable
10	NETWORK/MFD	RJ45: Connects the radar to the navigation Ethernet network

LED Indicator lights

LED	Color	Indication
Power	Green steady	Power is applied and the radar is turned on (by either
		remote power on or power control jumper set to Auto).
Comms	Green fast flashing	NMEA 2000 traffic present
	Green slow flashing	RI-12 with pedestal communication active
	Off	No NMEA 2000 data and no communication with the pedestal
Status	Green steady	Radar is transmitting
	Orange	Radar is in standby
	Red	Low input voltage < 10 V DC (RI-12 has stopped sending power to the pedestal
	Red flashing	Power supply fault
Ethernet	Green fast flashing	Successful communications with an MFD
	Green steady	Physical connection to an Ethernet device exists but there is no communication with any MFD
	Off	No connection to any other active Ethernet device

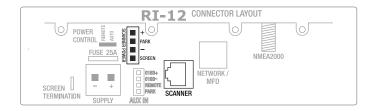
Pedestal Interconnection cable

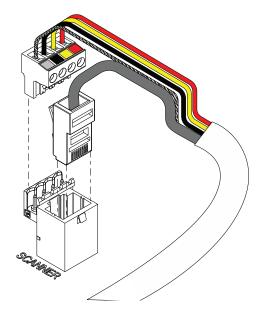
The interconnection cable connects the radar pedestal to the RI-12 Interface module. The cable connects to the pedestal using a 14 pin connector. The pedestal 14 pin connector can be set to either rear exit or discrete exit underneath the pedestal. (see "Pole or tower mount: Discreet cable connection" on page 19)

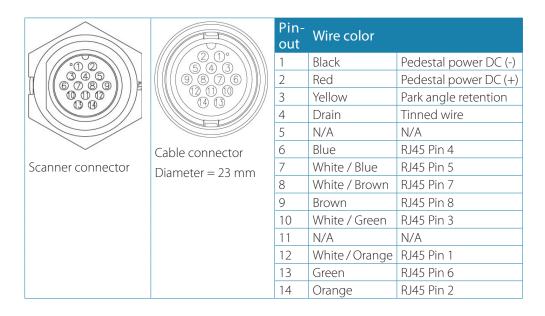
Note: Protect the connectors especially the RJ45 connector when pulling cable through the boat and avoid putting strain on to the connectors.

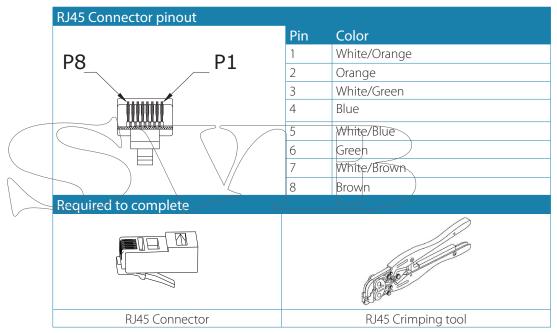
The interconnection cable is 9 mm in diameter. A 14 mm hole will be required in order for the RJ45 (Interface module end) to pass through bulkheads or 24 mm hole for the 14 pin connector (pedestal end) to pass though.

Bun the interconnection cable between the pedestal and the location of the RI-12 Interface module.









Connect the power cable

accordingly.

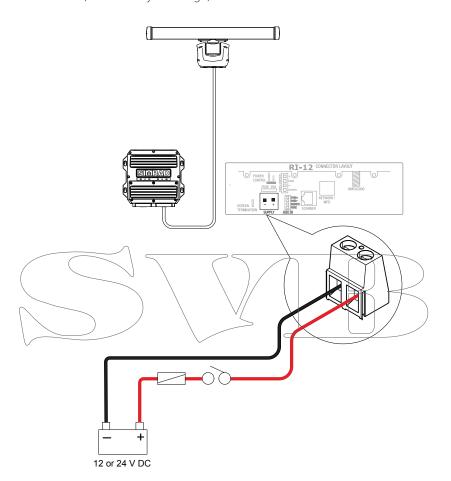
Power for the radar is connected to the RI-12 Interface module. The radar requires either a 12 or 24 V DC supply capable of delivering 15A for 12V system and 8A for 24V system continuous. The RI-12 is protected against reverse polarity, over and under voltage. The RI-12 must be connected to a dedicated fuse/circuit breaker. The fuse/circuit breaker should be labeled

Voltage		Cable length		
	2 m (6.6 ft)	5 m (16.4 ft)	10 m (32 ft)	20 m (66 ft)
12 V DC	2.1 mm (12-AWG)	3.3 mm (8-AWG)	4.1 mm (6-AWG)	N/A
24 V DC	1.3 mm (14-AWG)	2.1 mm (12-AWG)	3.3 mm (8-AWG)	4.1 mm (6-AWG)

- → Note: Above values in mm=diameter of the cable conductor
- → *Note:* The RI-12 has an optional remote power control mode that can enable a compatible multifunction display or ignition switch to control the power state of the radar (see "Remote power control" on page 27)

Connecting power

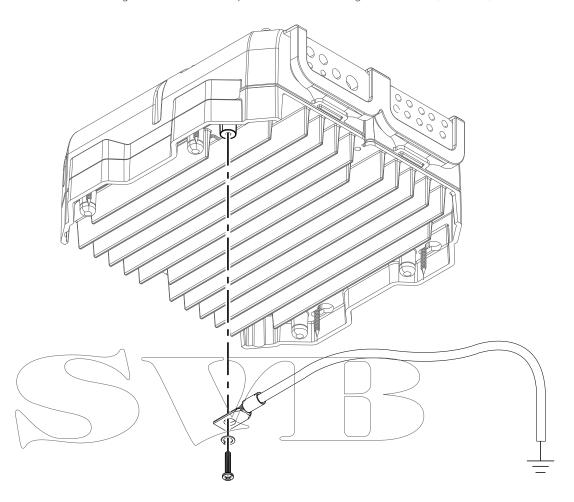
- 1. Strip away approximately 10 mm (0.4") of the insulation at the end of each core of the power cable
- 2. Unscrew the retention screw from the positive input connector (identified by the + sign) on the radar processor
- 3. Insert the bare end of the positive wire into the positive power cable input connector to make a connection
- **4.** Tighten the holding screw to hold the positive wire in place. Gently pull on the positive wire to ensure that it is secured
- 5. Repeat this process to connect the negative wire to the negative power cable input connector (identified by the sign)



Grounding requirements

The RI-12 has a chassis ground terminal on the underside of the case. The chassis ground is DC isolated from power (–ve) to eliminate the risk of galvanic corrosion.

It is recommended that the RI-12 ground is connected to the vessels bonded ground or a non bonded RF ground at the closest possible location, using 12 AWG wire (or thicker):



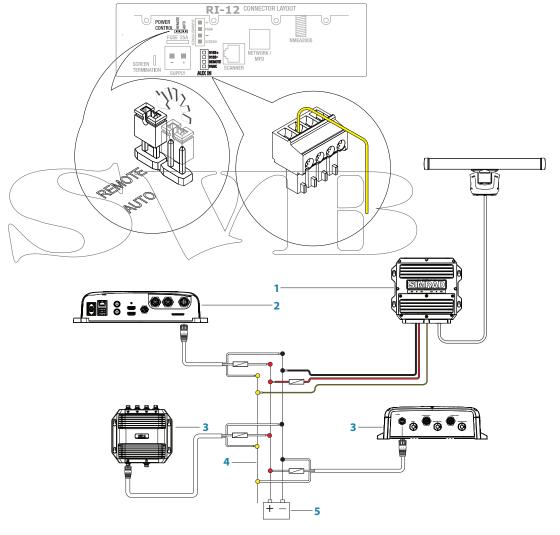
Remote power control

Remote power control is a feature that allows the power state of the radar to be controlled either from a switch or when a compatible multifunction display is powered on or off.

- → **Note:** The power control jumper must be moved from AUTO to REMOTE for the radar to use the remote power on function.
- → Note: +V DC (5 V DC 32 V DC) from either a multifunction display set as power control master or a switch can be applied to the REMOTE port of the AUX IN connector for the remote power on to function.

Connect the yellow wire to external wake up of a compatible multifunction display to the remote input. The radar will turn on when the display is turned on. The display must be set to 'Master' under Power Control. (Please refer to the displays user manual)

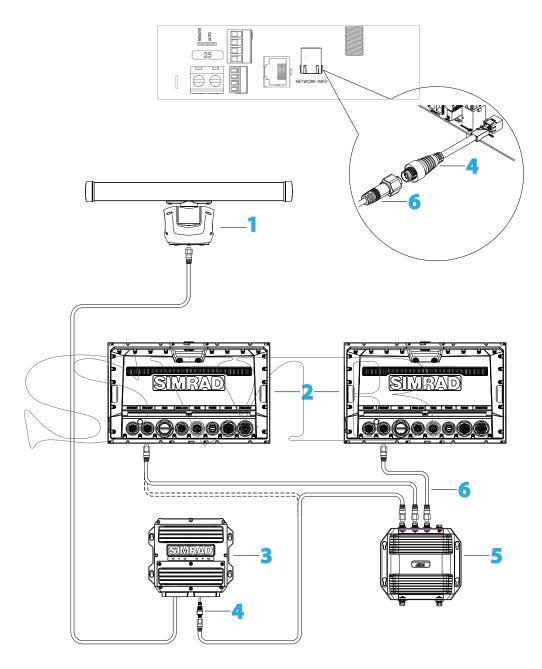
- → **Note:** If the radar is turned off via remote power control while transmitting, The radar will auto park the antenna before shutting down.
- → *Note:* There must be a common batt -ve for all devices on power control bus.



No.	Description
1	Halo® RI-12 Interface module
2	NSO evo2 or other multifunction display (one or more multifunction display needs to be set to power control master)
3	Other Simrad device with remote power control
4	Power control bus
5	DC Power

Network

An Ethernet network is used to distribute the radar data to compatible multi-function displays. The RI-12 is connected to the Ethernet network using a standard Simrad Ethernet cable and the supplied adapter cable. The RI-12 can be connected either directly to any Simrad compatible MFD or to a network switch such as an NEP-2 or SonarHub.



No.	Description
1	Halo® pulse compression radar pedestal and antenna
2	Multi-function displays
3	RI-12 interface module
4	RJ45 to 5 pin yellow Ethernet adapter (p/n 000-11246-001)
5	NEP-2 or device with a built in Ethernet switch
6	Ethernet cables. Supplied with a 1.8 m (6 ft). The RI-12 can connect either directly to a multifunction display or to other an Ethernet switch such as NEP2 or SonarHub

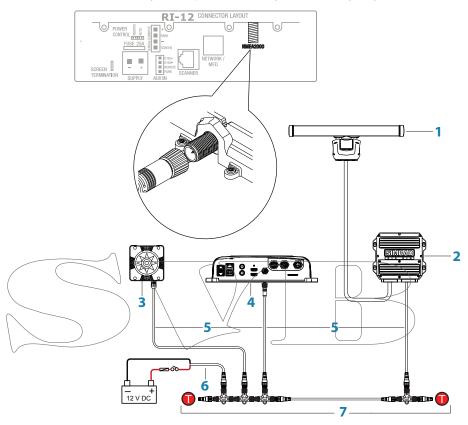
NMEA 2000

The RI-12 can be connected to a Micro-C NMEA 2000 network to receive heading and position information.

A heading sensor is required for the following functionality;

- MARPA: heading at 10 Hz or faster is required for the radar to calculate MARPA tracking. Heading must also be connected to the display.
- Radar Chart overlay and North-up: Heading is required by the multi-function display For heading sensors that output NMEA 0183 (see "NMEA 0183" on page 30)

For magnetic heading sensors, heading calibration should be performed before using MARPA or Chart Overlay, and repeated annually, and after any major structural changes to the vessel.

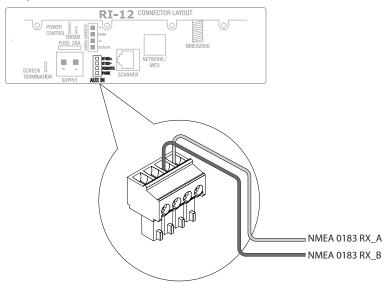


No.	Description
1	Halo® radar pedestal and antenna
2	RI-12 interface modules
3	NMEA 2000 compliant heading sensor
4	Compatible multifunction display
5	Micro-C drop cables
6	Network power 12 V DC
7	Micro-C backbone (NMEA 2000) with terminators

NMEA 0183

The RI-12 has one NMEA 0183 (RS422) to accept heading and position information. The NMEA 0183 port is auto sensing and can accept 4800, 9600, 19200 or 38400 baud rates.

Sentences used HDG, HDT, HDM, GGA, GLL, RMC, VTG. Heading should be at a minium of 10 Hz update rate.



RI-12 heading source selection:

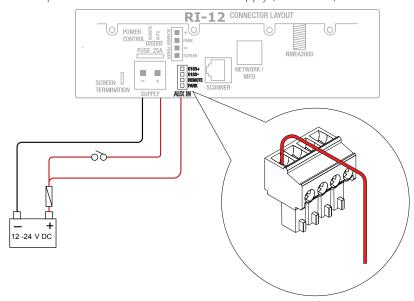
The RI-12 receives heading via the NMEA 2000 network and transmits this data to the radar, where MARRA processing is performed.

For Simrad installations with more than one heading source the RI-12 will use the Simrad group source. The source used by the Simrad group can be viewed or changed via the multifunction display in the Settings>Network>Sources... menu.

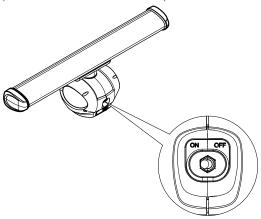
Note: If an NMEA 0183 heading source is connected the RI-12 will use this. It will ignore a NMEA 2000 heading source.

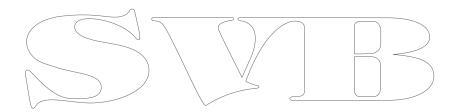
Antenna park

The Halo® Pulse Compression Radar has the ability to stop rotating the antenna and hold it at a predetermined angle in relation to the ships heading line. The park angle is set in the display (see "Adjust open array park angle" on page 34). In conjunction with this setting there is a park angle retention feature which is a very low current electromagnetic brake that will provide resistance for the antenna to maintain a parked angle against wind and movement. The park brake requires a continuous low current DC supply (10-32 V DC). This draws less than 100uA.



When all connections have been made and checked the safety switch on the rear of the pedestal can be set to the ON position







Setup and configuration

Setup and configuration of the Halo® radar has been simplified compared to traditional pulse radars. There is no zero range adjustment (time delay), no warm up time, and no burn in required.

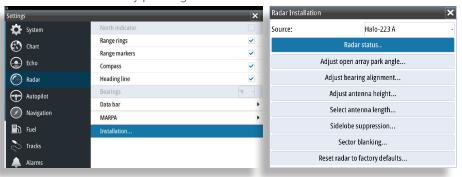
Source

On the radar page, choose the radar to be setup using the source drop down. MENU>SOURCE When setting up the Halo Pulse Compression radar choose either Halo-A or Halo-B

→ Note: Following settings require the radar to be in Transmit mode. MENU>TRANSMIT

Entering radar setup on your display

Enter radar installation by pressing MENU > SETTINGS > RADAR > INSTALLATION.



There are three essential steps to setup the Halo® radar:

- Set antenna length
- Set antenna height
- Set bearing alignment



Select the antenna length

Select the correct length of antenna. Select Save to exit back to the radar installation page.

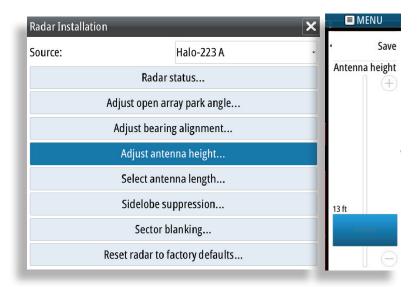




Adjust antenna height...

Set the radar scanner height. Use the slider control or the "+" or "-" buttons to set the value then SAVE.

→ Note: The antenna height is the height of the antenna above the water line. It is very important to set the antenna height configured correctly as this will affect the sea clutter function. Do not set the height to 0.



Adjust bearing alignment...

Adjust the heading marker. This is to align with the heading marker on the screen with the center line of the vessel, this will compensate for any slight misalignment of the pedestal during installation. Any inaccuracy will be evident when using MARPA or chart overlay.

Point the boat towards a stationary isolated object. Adjust the bearing alignment so the heading line touches the end of the same object.

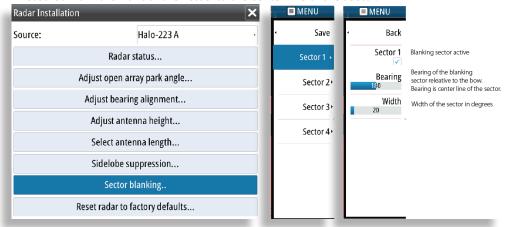
Use the slider control or the "+" or "-" buttons to set the value then SAVE



Sector blanking

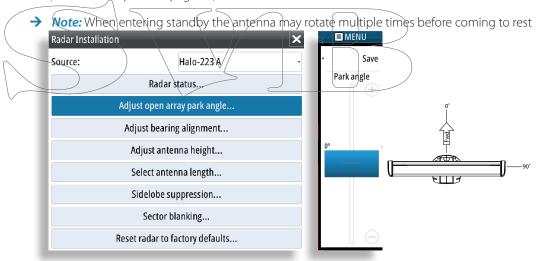
On vessels where the radar is installed in close proximity to a mast or structure that could cause unwanted reflections or interference to appear on the radar image. Use the sector blanking feature to stop the radar from transmitting in the direction up to four sectors.

→ **Note:** Sectors are setup relative to the heading line of the radar. The bearing of the sector is measured from the front of the vessel to the center line of the sector.



Adjust open array park angle

The park angle is the final resting position of the antenna relative to the heading line of the radar when the radar is set to standby. The antenna will stop rotating at the desired offset. Optionally the antenna can be held in place against wind by connecting the antenna park wire (see "Antenna park" on page 30).



Sidelobe suppression...

→ **Note:** This control should only be adjusted by experienced radar users. Target loss in harbour environments may occur if this control is not adjusted correctly.

Occasionally false target returns can occur adjacent to strong target returns such as large ships or container ports.

This occurs because not all of the transmitted radar energy can be focused into a single beam by the radar antenna, a small amount energy is transmitted in other directions.

This energy is referred to as sidelobe energy and occurs in all radar systems.

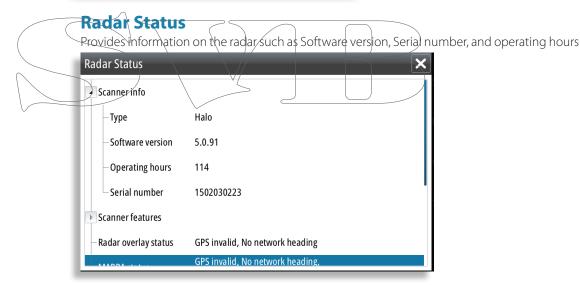
The returns caused by sidelobes tend to appear as arcs:

When the radar is mounted where there are metallic objects near the radar, sidelobe energy increases because the beam focus is degraded. The increased sidelobe returns can be eliminated using the Sidelobe Suppression control in the Radar installation menu.

By default this control is set to Auto, and normally should not need to be adjusted. However if there is significant metallic clutter around the radar, sidelobe suppression may need to be increased. The control should be adjusted as follows:

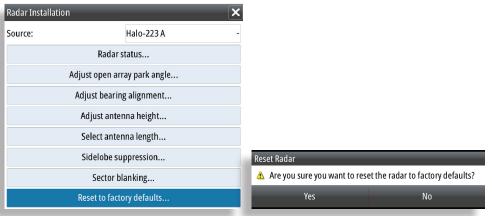
- 1. Set radar range to between 1/2 nm to 1 nm and Sidelobe Suppression to Auto
- 2. Take the vessel to a location where sidelobe returns are likely to be seen. Typically this would be near a large ship, container port, or metal bridge
- 3. Traverse the area until the strongest sidelobe returns are seen
- **4.** Change Auto sidelobe suppression to OFF then select and adjust the sidelobe suppression control until the sidelobe returns are just eliminated. You may need to monitor 5-10 radar sweeps to be sure they have been eliminated
- 5. Traverse the area again and readjust if sidelobes returns still occur
- 6. Exit the installation menu





Reset Radar to factory defaults

Reset to factory defaults function will only reset radar control settings, not installation settings.

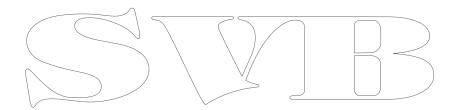


Control pedestal accent lighting

The Halo™ Pulse Compression Radar pedestal has a blue accent light. The LED accent light has four light levels controlled from the radar menu.

→ *Note*: The accent light can only be adjusted when the radar is in standby

Halo™ Pulse Compression Radar's blue 4 level static accent pedestal lighting may not be approved for use in your boating location. Please check your local boating regulations before turning the blue accent lights ON.



7

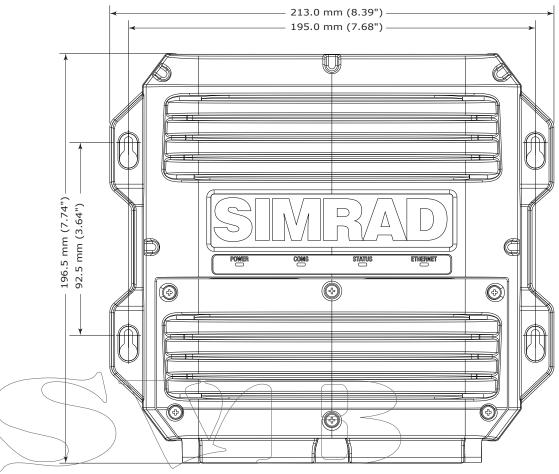
Specifications

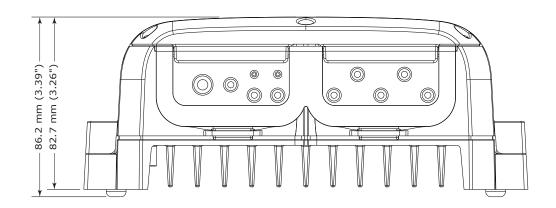
	Description	25 W Halo® Pulse Compres	ssion Radar System		
	Description	25 W Halo® Pulse Compression Radar System System consists of radar pedestal, antenna, Interconnection			
		cable and RI-12 Interface Module.			
	Type of emission	FCC/IC/R&TTE Type Certification			
	71	FCC ID: RAYHALO			
		IC ID: 4697A-HALO R&TTE: Emissions compliant to SM1541-4 (including			
	Environmental	dB/dec future design of	ojectives)		
	Operating Temperature	25°C to 155°C (12°E 121	°E\		
	Relative humidity	-25°C to +55°C (-13°F - 131°F) IEC60945 Exposed product			
	Shock and Vibration	IEC60945 Exposed product and 20G, 100,000 cycle			
	UV	IEC60945 Exposed produc	•		
	Waterproofing	IPX6 70 knots for 3', 4', and 6' antenna at 48 rpm with RI-12			
	Relative wind velocity				
	Power				
	Power consumption	150 W (peak) at maximum	wind velocity		
		· ·	40 W (average) at zero wind velocity		
		=	er + RI-12 in Standby mode		
	DC input	R-12: 10.8 V DC to 31.2 V DC (12/24			
	·		6 V DC nominal generated by RI-12		
	Power up time	16-25 seconds from PO			
	·		10 25 Seconds north Ovventor to TIV (Norwill		
(Physical Height	448 mm (17.64")			
	Antenna swing circle diameter	3 ft model: 1141 mm (3.5.1			
		4 ft model: 1431 mm (4.5 f			
		6 ft model: 2045 mm (6.5 f			
	Component weights	Pedestal	18.75 Kg (41.3lb)		
		Antenna 3 ft	4.1 Kg (9.0 lb)		
		Antenna 4 ft	4.9 Kg (10.8 lb)		
		Antenna 6 ft	6.5 Kg (14.3 lb)		
		RI-12	1.6 Kg (3.5 lb)		
		10 m (33 ft) Cable	1.1 Kg (2.4 lb)		
		20 m (66 ft) Cable	2.3 Kg (5.0 lb)		
		30 m (100 ft) Cable	3.4 Kg (7.5 lb)		
	Antenna				
	Instrumented range	3 ft model: 48 nm 4 ft model: 64 nm 6 ft model: 72 nm			
	Transmitter	Solid state module with no long term transmitter pow			
		degradation			
	Rotation		Min 20 rpm at Max 70 kts).		
		Software controlled in modes			
	Beam width	3 ft: 2.4°+/-10% (-3 dB width) – 1.7 deg with Beam sharpening mode ON 4 ft: 1.8°+/-10% (-3 dB width) – 1.3 deg with Beam			
		sharpening mode ON			
			vidth) - 0.8 deg with Ream		
			ft 1.2°+/-10% (-3 dB width) - 0.8 deg with Beam harpening mode ON		
	Beam width Vertical	25° +/-20 % (-3 dB width)			
	Plane of polarization	Horizontal Polarization			
	Sidelobe level 3 ft	Below -23 dB max. (within ±10°)			
	SIGCIONC ICVCI J IL	DCIOVY ZJ UD IIIAA. (WILL	Below –30 dB max. (outside ±10°)		
		Polow 20 dD (cido +10°)		

Side lobe level 4 ft	Below -23 dB max. (within ±10°)
	Below -30 dB max. (outside $\pm 10^{\circ}$)
Side lobe level 6 ft	Below -23 dB max. (within ±10°)
	Below -30 dB max. (outside $\pm 10^{\circ}$)
Transmitter frequency	Synthesized - Upper half of X-Band 9.410 - 9.495 GHz
Peak power output	$25 \mathrm{W} \pm 10\%$ under any transmit condition – up to 10%
	duty cycle max
Pulse length/PRF and	Pulse length: 0.04 usec
Compression ratio	Chirp length:2-96 usec
	Chirp Bandwidth: 2-32 MHz
	Up to 1 pulse and 5 chirps in a burst with burst repetition rate of 500-2000. Range and mode dependent.
	Effective Pulse Compression Ratio less than 150 in all modes.
SART/RACON Triggering	Yes – trigger distance: about 1nm max – weather, sea state, and SART position dependent
Duplexer	Circulator and isolator
Mixer	MIC front-end
IF section	Center frequency: 28.625 MHz
	Bandwidth: 40 MHz max.* A/D; 16 bit 115 MSPS
	*Narrower bandwidths defined by signal processing
Noise figure	5 dB (Average) at front-end input.
	STD. 1.0 m (3.3 ft) Steer 0.5 m 1.6 ft)
Z-OHIDASS/Sale distance	3 2. 1.0
Compass safe distance	31D. 1.0 III (3.3 II) 3teel 0.3 III 1.0 II)
Other	
	Ethernet 10/100 Base-T for radar data and control
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via R)-12
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS USED
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS-USED 127250 - Vessel Heading
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS-USED 127250 - Vessel Heading 127251 - Rate of Turn
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS-USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA 2000 PGNS USED 127250 - Vessel Heading 127251 - Rate of Turn
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS-USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update 129026 - COG & SOG, Rapid Update
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS-USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update 129026 - COG & SOG, Rapid Update 129029 - GNSS Position Data
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA 2000 PGNS USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update 129026 - COG & SOG, Rapid Update 129029 - GNSS Position Data 130818 - Proprietary
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS-USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update 129026 - COG & SOG, Rapid Update 129029 - GNSS Position Data 130818 - Proprietary NMEA 0183 Input via RI-12 Sentenses used by the radar application. HDG, HDT,
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA2000 PGNS USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update 129026 - COG & SOG, Rapid Update 129029 - GNSS Position Data 130818 - Proprietary NMEA 0183 Input via RI-12 Sentenses used by the radar application. HDG, HDT, HDM, GGA, GLL, RMC, VTG.
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA-2000 PGNS-USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update 129026 - COG & SOG, Rapid Update 129029 - GNSS Position Data 130818 - Proprietary NMEA 0183 Input via RI-12 Sentenses used by the radar application. HDG, HDT, HDM, GGA, GLL, RMC, VTG. Baud rate: Auto sense 4800, 9600, 19200 or 38400
Other	Ethernet 10/100 Base-T for radar data and control Micro-C male / NMEA2000 via RI-12 NMEA2000 PGNS USED 127250 - Vessel Heading 127251 - Rate of Turn 129025 - Position, Rapid Update 129026 - COG & SOG, Rapid Update 129029 - GNSS Position Data 130818 - Proprietary NMEA 0183 Input via RI-12 Sentenses used by the radar application. HDG, HDT, HDM, GGA, GLL, RMC, VTG. Baud rate: Auto sense 4800, 9600, 19200 or 38400 Antenna park
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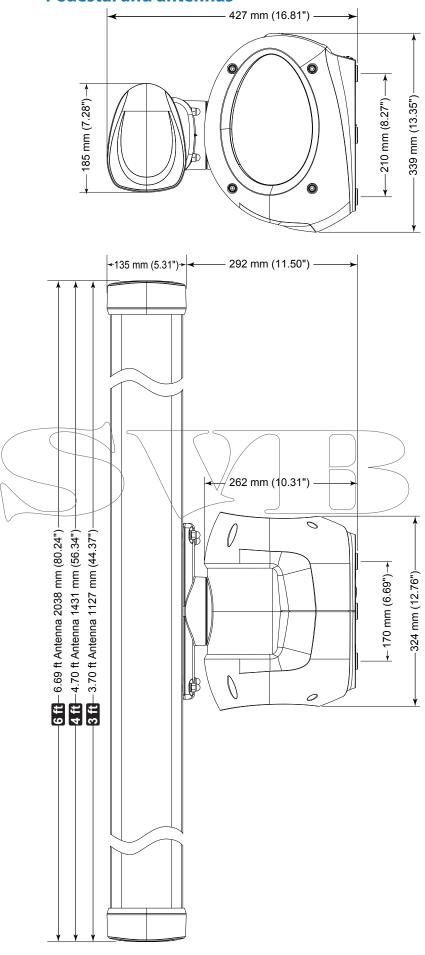
Drawings

RI-12

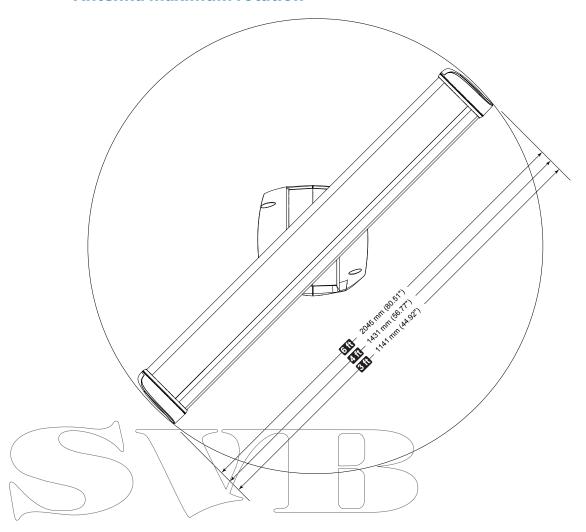




Pedestal and antennas



Antenna maximum rotation



9

Spare Parts

		Part Number	Description	
		000-11463-001	Halo pedestal	
	ð	000-11464-001	3 ft (1127 mm) antenna	
	6	000-11465-001	4 ft (1431 mm) antenna	
		000-11466-001	6 ft (2038 mm) antenna	
		000-11467-001	RI-12 Radar interface module	
		A4010211	Broadband scanner interconner 10 m (33 ft)	ection cable
6		AA010212	Broadband scanner interconne 20 m (65.6 ft)	ection cable
		AA010213	Broadband scanner interconne 30 m (98.5 ft)	ection cable
	>	000-11246-001	Adapter cable: yellow Etherner male. 150 mm (5.9")	t female to RJ45
000-00127-28		et cable		0.6 m (2 ft)
000-0127-51		et cable		1.8 m (6 ft)
000-0127-29		et cable		4.5 m (15 ft)
000-0127-30	7-37 Ethernet cable 15.2			7.7 m (25 ft) 15.2 m (50 ft)
000-012/ <i>-</i> 3/				13.2 111 (30 11)
24005936				
24006694	AT10HD NMEA0183 heading to/ NMEA 2000 converter. (SimNet connector).			

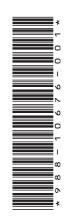
Third party mounting options

Seaview (<u>www.seaviewglobal.com</u>)

Image	Seaview part no.	Description
	PMF-57-M1	127 mm (5.7") tall forward leaning mount
	PMA-57-M1	127 mm (5.7") tall aft leaning mount
	ADA-R1	Top plate
	ADA-HALO-3	Adapter plate. Used in conjunction with ADA-R1 and a mounting tower
	RW4-7	4° Angled wedge adapter
	ADA-HALO-2	Adapter for replacing 3G/4G, Raymarine and Garmin radars with Halo
	PMA-DM2-M2	Dual mount. (Not for 6 ft Halo)

Scanstrut (www.scanstrut.com)

Image	Scanstrut Part No.	Description
	<u>APT6003</u>	150 mm (6") Aluminium PowerTower® for Halo (3 ft, 4 ft, 6ft)
	DPT-40-SO3	Dual PowerTower® for 40 cm satcom plus Halo 3 ft or 4 ft
	DPT-60-SO3	Dual PowerTower® for 60 cm satcom plus Halo 3 ft or 4 ft





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